

Note on calculating reload values FFMC8L

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When using timers in reload mode, the main intention is to generate circular interrupts with a fixed reload time. But when interrupt service routines are called, a certain overhead will be produced by the compiler (context save !). This note shows how to calculate the correct reload value taking in account the produced extra code.

In this example, a rectangular signal with a frequency of 1,5 kHz should be produced on pin 40. The reload value has to be calculated to obtain this period. The positive width of the signal is fixed and much smaller than the period itself.

The diagram below shows the signal and the ISR procedure : When the interrupt is signaled and processed immediately, which would assume a certain priority and no other interrupt currently active, the context will be saved on the stack after the ISR-subroutine is called. This context save is produced by the compiler. After that the intended taks can be processed – in this case a signal on pin 40 with a definite width.



Fig. 1. : Producing a signal on pin 40 using a 16-bit(reload)-timer interrupt

In the produced code, the offset (due to calling ISR and context save) takes 64 cycles (40_{hex}) which must be included in the calculation :

$$Reload = FFFF_{hex} - (f_c / (4 f_{int})) + 40_{hex} \quad mit: \quad f_c: Quartzfreq.$$
$$f_{int}: Interruptfreq.$$

In this example : With $f_c = 10$ MHz and $f_{int}=1500$ Hz : $Reload=F9BD_{hex}$

<u>Interrupt-Service Routione 16-bit-Timer :</u>

(C-Source-code printed bold)

before calling ISR : finish actual command and save PS and address on stack

approx. 10-14 cycles

221: {	
C2BA: 40 PUSHW A	4
C2BB: 43 XCHW A,T	2
C2BC: 40 PUSHW A	4
C2BD: F3 MOVW A,EP	2
C2BE: 40 PUSHW A	4
C2BF: 41 PUSHW IX	4
C2C0: F1 MOVW A,SP	2
C2C1: E2 MOVW IX,A	2
C2C2: 08 MOV A,R0	3
C2C3: 10 SWAP	2
C2C4: 09 MOV A.R1	3
C2C5: 40 PUSHW A	4
222: TMCR - 0x22: /* Int enable egain */	•
$C_{2}C_{6}$: 851822 MOV 18 #22	4
223. TCHD = $0xE6$. /* Delead value */	7
C2C0: 8510E6 MOV = 10 #E6	4
$224. \text{ TCL } \mathbf{D} = 0.229.$	4
224: ICLK = $0X3D$; C2CC: $951A2D$ MOV 1A $#2D$	4
$C_2CC: \delta_{3}TA3D INOV TA, \#3D$	4
225: $TCS = 1$; /* start counter again */	4
C2CF: A818 SETB 18:00	<u>4</u>
	64 cycles
226: PDR4_0 = 1; /* show pulse on PIN 40 */	
C2D1: A80F SETB 0F:00	
227: wait(20);	
227: wait(20); C2D3: E40014 MOVW A,#0014	
227: wait(20); C2D3: E40014 MOVW A,#0014 C2D6: 40 PUSHW A	
227: wait(20); C2D3: E40014 MOVW A,#0014 C2D6: 40 PUSHW A C2D7: 31C04B CALL \wait	
227: wait(20); C2D3: E40014 MOVW A,#0014 C2D6: 40 PUSHW A C2D7: 31C04B CALL \wait C2DA: 50 POPW A	
227: wait(20); C2D3: E40014 MOVW A,#0014 C2D6: 40 PUSHW A C2D7: 31C04B CALL \wait C2DA: 50 POPW A 228: PDR4_0 = 0;	
227: wait(20); C2D3: E40014 MOVW A,#0014 C2D6: 40 PUSHW A C2D7: 31C04B CALL \wait C2DA: 50 POPW A 228: PDR4_0 = 0; C2DB: A00F CLRB 0F:00	
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