Motorola Semiconductor Engineering Bulletin

EB282

Using the Output Compare Function on the Time Processor Unit and an Example that Includes PPWA

By Sharon Darley Austin, Texas

Introduction

The output compare function (OC) on the time processor unit (TPU) has three modes of operation:

- Read TCR1/TCR2
- Host-initiated pulse
- Continuous pulse

In the read TCR1/TCR2 mode of operation, the TPU reads the most recent values of TCR1 and TCR2 and returns them in memory locations \$FFFFEC and \$FFFFEE. In the host-initiated pulse mode, the TPU performs the same function as in the read TCR1/TCR2 mode of operation, except that it also immediately forces the pin high or low as specified in the PSC field. It then forces the pin again at a designated time in the future. In the continuous pulse mode, the TPU outputs a continuous train of 50% duty cycle pulses. The OC function can receive links (a link is a service request from another channel) only in the continuous mode.

For a detailed discussion of the OC function and all of its parameters, see *Output Compare TPU Function (OC*), Motorola document order number TPUPN12/D. This document can be ordered from Literature Distribution Center or it can be accessed on the Worldwide Web at



http://www.mcu.motsps.com/lit/manuals/tpulitpak/pdf.html. The application note *Timing Performance of TPU I/O Hardware*, Motorola document order number AN1236/D, also has a detailed example of how to initialize the OC function.

Using OC Function

This section gives several examples of how to use the OC function in the host-initiated pulse mode and also in the continuous pulse mode. These examples were assembled on the IASM32 assembler, available from P&E Microsystems. They are written for CPU32-based microcontrollers such as the MC68332 and MC68333. Translating the examples to CPU16 code mainly involves changing the MOVE instructions to LDD and STD instructions. These examples use these equates:

TPUMCR	EQU	\$FFFE00
TICR	EQU	\$FFFE08
CIER	EQU	\$fffe0a
CISR	EQU	\$FFFE20
CFSR3	EQU	\$FFFE12
HSQR1	EQU	\$FFFE16
CPR1	EQU	\$FFFE1E
HSRR1	EQU	\$FFFE1A
PRAM0_0	EQU	\$FFFF00
PRAM0_1	EQU	\$FFFF02
PRAM0_2	EQU	\$FFFF04
PRAM0_3	EQU	\$FFFF06
PRAM0_4	EQU	\$FFFF08
PRAM1_0	EQU	\$FFFF10
PRAM1_1	EQU	\$FFFF12
pram1_2	EQU	\$FFFF14
pram3_0	EQU	\$FFFF30
pram3_2	EQU	\$FFFF34
pram3_3	EQU	\$FFFF36

Host-Initiated Pulse Mode

Example 1 This example initializes channel 0 in the host-initiated pulse mode. The pin will be forced high immediately upon initialization and will then be forced low \$2000 TCR1 counts after initialization.

ORG \$400	; begin the program at \$400
MOVE.W #\$0003,(CPR1).L	; give channel high priority (CPR1)
MOVE.W #\$000E,(CFSR3).L	;select OC function in CFSR3
MOVE.W #\$0000,(HSQR1).L	;matches and pulses scheduled (HSQR1)
MOVE.W #\$0089,(PRAM0_0).L	;PSC = high, PAC = low
MOVE.W #\$2000,(PRAM0_1).L	;Offset = \$2000
MOVE.W #\$00EC,(PRAM0_2).L	;REF_ADDR1 = TCR1
MOVE.W #\$0001,(HSRR1).L	;host service request for host-init mode
BRA LOOP	

LOOP

Example 2 This example initializes channel 0 in the host-initiated pulse mode. The output of the pin will be a continuous pulse train. The continuous train is accomplished by re-initializing the channel in the interrupt routine.

NOTE: Make sure that the vector base register (VBR) is set to \$400 before running this program

	ORG \$40	00	
	MOVE.W	#\$00E0,(CFSR3).L	;channel 0 output compare
	MOVE.W	#\$0000,(HSOR1).L	;matches and pulses scheduled
	MOVE.W	#\$000C,(CPR1).L	;high priority
	ANDT.W	#\$0000.(CISR).L	iread and clear interrupt status register
	MOVE L	#TNT.(\$604) T	starting address of interrupt routine
			i(assuming VBR = \$400)
	ORTW		; TARB field = 5
	MOVE W	$\pm \pm $	interrupt level 6. vector \$80
	ANDT.W	#\$F5FF.SR	; mask out interrupts at level 5 and below
			assuming reset state of SR
	MOVE.W	#\$008E/(PRAM1 0).L	;psc=0,pac=toggle, capture/match tcr1
	MOVE.W	#\$0200,(PRAM1 1).L	iter1 offset from REF ADDR1 for channel 1
	MOVE.W	#\$00EC,(PRAM1 2).L	;REF ADDR1 = tcr1 for channel 1
	MOVE.W	#\$0004,(HSRR1).L	;host-init pulse request, ch 1 will go
			;hiqh
	MOVE.W	#\$0002,(CIER).L	;enable interrupt for channel 1
MNLOOP	BRA MNI	LOOP	-
INT			
	ANDI.W	#\$FFFD,(CISR).L	;read and clear interrupt
	MOVE.W	(PRAM1_0).L,D0	
	CMPI.B	#\$8E,D0	;see whether ch1 should go low or high
	BNE NX	Г	
	MOVE.W	#\$0089,(PRAM1_0).L	;capture/match tcr1,psc=high,pac=low
	MOVE.W	#\$001A,(PRAM1_2).L	;REF_ADDR1=ACTUAL_MAT_TIME for channel 1
	MOVE.W	#\$0004,(HSRR1).L	;channel 1 will go low
	BRA EN		
NXT	MOVE.W	#\$008E,(PRAM1_0).L	;psc=low,pac=toggle, capture/match tcr1
	MOVE.W	#\$0004,(HSRR1).L	;host-init pulse request, ch 1 will go
			;high
	EN	RTE	
	_		
Continuous Pul	se	This example uses OC	with the PPWA function to divide the input
Mode	f	requency to the PPWA	channel by four. The scaling factor is located in
	4	be RATIO field of the C	C function A RATIO of SEE corresponds to a
	l		
	ę	scaling factor of 1. RAT	IO scales the number at the address pointed to

In this example, RATIO scales the period accumulation, indicated by PPWA LW.

The PPWA function repeatedly accumulates 16 input periods and then generates a link to the OC function. The OC function scales the

by REF_ADDR2 to determine the OC pulse HIGHTIME (not the period).

EB282

Engineering Bulletin

accumulated period and then generates the scaled output waveform. The PPWA function is on channel 0, and the OC function is on channel 3.

A function generator (or other type of signal generator) must be physically connected to channel 0. The frequency of the input signal must be smaller than \$FFFF (65,535) TCR1 counts, since PPWA is initialized in the 16-bit mode. The output pulse train can be observed on channel 3. No other physical connections are necessary.

	ORG MOVE.W MOVE.W MOVE.W MOVE.W	\$400 #\$E00F,(CFSR3).L #\$0001,(HSQR1).L #\$00FF,(CPR1).L #\$00C0,(TPUMCR).L	<pre>;ppwa 0, oc 3 ;16 bit mode, links, pulse accum. ;high priority ;tcrl as fast as possible</pre>
*** PPWA initia	alizatio	on	
	MOVE.W MOVE.W MOVE.W	#\$310B,(PRAM0_0).L #\$1000,(PRAM0_1).L #\$FF00,(PRAM0_4).L	<pre>;pulse accumulate, link to ch 3 ;max count = 16 (\$10) ;service rate = slowest</pre>
***OC initiali:	zation		
	MOVE.W MOVE.W	#\$008A,(PRAM3_0).L #\$2004,(PRAM3_2).L	<pre>;low on match, low at init. ;ref addr1 = lastaccum, ratio=1/4. ;Here, since PPWA is a period accum. and, ;not a pulse hightime accum., PPWA_LW ;must be divided by two. Thus, ;RATIO = (OC period/PPWA_LW) x (255/2) ;Since the desired ratio of the output ;period to the input period is 4/1, and ;PPWA_LW represents 16 periods, ;(OC pd./PPWA_LW) = (4/1) x (1/16) =1/4 ;Thus, RATIO = (1/4) x (255/2) = \$20.</pre>
DONE	MOVE.W MOVE.W BRA DOM	#\$0A04,(PRAM3_3).L #\$00C2,(HSRR1).L NE	<pre>;ref addr2=ppwalw, refaddr3=lastaccum ;host service requests</pre>

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Motorola data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights or the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death massociated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola and (**A**) are registered trademarks of Motorola, Inc. Motorola, Inc. is an Equal Opportunity/Affirmative Action Employer.

How to reach us:

USA/EUROPE/Locations Not Listed: Motorola Literature Distribution, P.O. Box 5405, Denver, Colorado 80217.

1-800-441-2447 or 1-303-675-2140. Customer Focus Center, 1-800-521-6274

JAPAN: Motorola Japan Ltd.: SPD, Strategic Planning Office, 141, 4-32-1 Nishi-Gotanda, Shinagawa-Ku, Tokyo, Japan, 03-5487-8488 ASIA/PACIFIC: Motorola Semiconductors H.K. Ltd., Silicon Harbour Centre, 2 Dai King Street, Tai Po Industrial Estate,

Tai Po, New Territories, Hong Kong, 852-26629298

Mfax™, Motorola Fax Back System: RMFAX0@email.sps.mot.com; http://sps.motorola.com/mfax/; TOUCHTONE, 1-602-244-6609; US and Canada ONLY, 1-800-774-1848

HOME PAGE: http://motorola.com/sps/



Mfax is a trademark of Motorola, Inc.

© Motorola, Inc., 1999