# Low-Voltage 1:10 Differential ECL/PECL/HSTL Clock Driver

The MC100EP111 is a low skew 1-to-10 differential driver, designed with clock distribution in mind. It accepts two clock sources into an input multiplexer. The ECL/PECL input signals can be either differential or single-ended if the VBB output is used. HSTL inputs can be used when the EP111 is operating under PECL conditions. The selected signal is fanned out to 10 identical differential outputs.

- 100ps Part-to-Part Skew typical
- · 35ps Output-to-Output Skew typical
- Differential Design
- V<sub>BB</sub> Output
- Low Voltage VEE Range of -2.25 to -3.8V for ECL
- Low Voltage V<sub>CC</sub> Range of +2.25 to +3.8V for PECL and HSTL
- 75kΩ Input Pulldown Resistors
- ECL/PECL Outputs

The EP111 is specifically designed, modeled and produced with low skew as the key goal. Optimal design and layout serve to minimize gate—to—gate skew within a device, and empirical modeling is used to determine process control limits that ensure consistent t<sub>pd</sub> distributions from lot to lot. The net result is a dependable, guaranteed low skew device.

## MC100EP111

LOW-VOLTAGE
1:10 DIFFERENTIAL
ECL/PECL/HSTL
CLOCK DRIVER



FA SUFFIX 32-LEAD LQFP PACKAGE CASE 873A-02

To ensure that the tight skew specification is met it is necessary that both sides of the differential output are terminated into  $50\Omega$ , even if only one side is being used. In most applications, all ten differential pairs will be used and therefore terminated. In the case where fewer than ten pairs are used, it is necessary to terminate at least the output pairs on the same package side as the pair(s) being used on that side, in order to maintain minimum skew. Failure to do this will result in small degradations of propagation delay (on the order of 10–20ps) of the output(s) being used which, while not being catastrophic to most designs, will mean a loss of skew margin.

The MC100EP111, as with most other ECL devices, can be operated from a positive  $V_{CC}$  supply in PECL mode. This allows the EP111 to be used for high performance clock distribution in +3.3V or +2.5V systems. Designers can take advantage of the EP111's performance to distribute low skew clocks across the backplane or the board. In a PECL environment, series or Thevenin line terminations are typically used as they require no additional power supplies. For more information on using PECL, designers should refer to Motorola Application Note AN1406/D.

The MC100EP111 may be driven single–endedly utilizing the  $V_{BB}$  bias output with the  $\overline{CLK0}$  input. If a single–ended signal is to be used, the  $V_{BB}$  pin should be connected to the  $\overline{CLK0}$  input and bypassed to ground via a 0.01  $\mu$ F capacitor. The  $V_{BB}$  output can only source/sink 0.2mA; therefore, it should be used as a switching reference for the MC100EP111 only. Part–to–Part Skew specifications are not guaranteed when driving the MC100EP111 single–endedly.

This document contains information on a new product. Specifications and information herein are subject to change without notice.



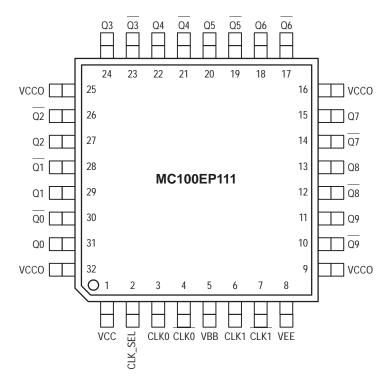


Figure 1. 32-Lead TQFP Pinout (Top View)

#### **PIN NAMES**

Pins	Function
CLK0, CLK0	Differential ECL/PECL Input Pair
CLK1, CLK1	Differential HSTL Input Pair
Q0:9, Q0:9	Differential PECL Outputs
CLK_SEL	Active Clock Select Input
VBB	V <sub>BB</sub> Output

#### **FUNCTION**

CLK_SEL	Active Input
0	CLK0, <u>CLK0</u>
1	CLK1, CLK1

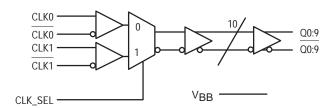


Figure 2. Logic Symbol

#### **ABSOLUTE MAXIMUM RATINGS\***

Symbol	Parameter	Min	Max	Unit
VCC	Supply Voltage	-0.3	4.6	V
VI	Input Voltage	-0.3	V <sub>CC</sub> + 0.3	V
IN	Input Current		±20	mA
T <sub>Stor</sub>	Storage Temperature Range	-40	125	°C

<sup>\*</sup> Absolute maximum continuous ratings are those values beyond which damage to the device may occur. Exposure to these conditions or conditions beyond those indicated may adversely affect device reliability. Functional operation under absolute—maximum—rated conditions is not implied.

#### THERMAL CHARACTERISTICS

Proper thermal management is critical for reliable system operation. This is especially true for high fanout and high drive capability products. Generic thermal information is available for the Motorola Clock Driver products. The means of calculating die power, the corresponding die temperature and the relationship to longterm reliability is addressed in the Motorola application note AN1545.

			–40°C		25°C			70°C			
Symbol	Characteristic	Min	typ Max	Min	typ	Max	Min	typ	Max	Unit	Condition
IEE	Internal supply cur- rent	45	85	60		95	65		105	mA	Absolute value of current
ICC	Output and Internal supply current	270	360	290		380	300		380	mA	All outputs termi- nated 50Ω to VCC-2.0V
IIN	Input current		150			150			150	μΑ	Includes pullup/pull- down resisters
VBB	Internally generated bias voltage	-1.38	-1.26	-1.38		-1.26	-1.38		-1.26	V	for VEE= -3.0 to -3.8 volts
VBB	Internally generated bias voltage	-1.38	-1.16	-1.38		-1.16	-1.38		-1.16	V	for VEE= -2.25 to -2.75 volts
VIH	Input HIGH voltage (CLK_SEL)	-1.165	-0.880	-1.165		-0.880	-1.165		-0.880	V	
VIL	Input LOW voltage (CLK_SEL)	-1.810	-1.475	-1.810		-1.475	-1.810		-1.475	V	
VPP	Input amplitude (CLK0,CLK0)	0.5	1.3	0.5		1.3	0.5		1.3	V	Difference of input ≈ VIH – VIL <sup>1</sup>
VCMR	Common mode voltage (CLK0,CLK0)	VEE+1.0	-0.3	VEE+1.0		-0.3	VEE+1.0		-0.3	V	Cross point of input ≈ average (VIH,VIL)
VOH	Output HIGH voltage	-1.30	-0.95				-1.20		-0.90		IOH = -30 mA
VOL	Output LOW voltage	-1.85	-1.40				-1.90		-1.50		IOL = -5  mA
VOUTpp	Differential output swing	350					500			mV	

### DC CHARACTERISTICS Vsupply: VCC=VCC0 = 2.25 to 3.80 volts, VEE = 0.0 volts

			10°C	2	25°C	70	°C		
Symbol	Characteristic	Min	typ Max	Min	typ Max	Min ty	γp Max	Unit	Condition
IEE	Internal supply cur- rent	45	85	60	95	65	105	mA	Absolute value of current
ICC	Output and Internal supply current	270	360	290	380	300	380	mA	All outputs termi- nated 50Ω to VCC-2.0V
IIN	Input current		150		150		150	μΑ	Includes pullup/pull- down resisters
VBB	Internally generated bias voltage	VCC-1.38	VCC-1.26	VCC-1.38	VCC-1.26	VCC-1.38	VCC-1.26	V	for VCC= 3.0 to 3.8 volts
VBB	Internally generated bias voltage	VCC-1.38	VCC-1.16	VCC-1.38	VCC-1.16	VCC-1.38	VCC-1.16	V	for VCC= 2.25 to 2.75 volts
VIH	Input HIGH voltage (CLK_SEL)	VCC-1.165	VCC-0.880	VCC-1.165	VCC-0.880	VCC-1.165	VCC-0.880	V	
VIL	Input LOW voltage (CLK_SEL)	VCC-1.810	VCC-1.475	VCC-1.810	VCC-1.475	VCC-1.810	VCC-1.475	V	
VPP	Input amplitude (CLK0,CLK0)	0.5	1.3	0.5	1.3	0.5	1.3	V	Difference of input ≈ VIH – VIL <sup>1</sup>
VCMR	Common mode voltage (CLK0,CLK0)	1	VCC-0.3	1	VCC-0.3	1	VCC-0.3	V	Cross point of input ≈ average (VIH,VIL)
Vdif	Differential input voltage (CLK1,CLK1)	0.4	1.9	0.4	1.9	0.4	1.9	V	Difference of input ≈ VIH – VIL
Vx	Input crossover voltage (CLK1,CLK1)	0.68	0.9	0.68	0.9	0.68	0.9	V	Cross point of input ≈ average (VIH,VIL)
VOH	Output HIGH voltage	VCC-1.30	VCC-0.95			VCC-1.20	VCC-0.90		IOH = -30 mA
VOL VOUTpp	Output LOW voltage Differential output swing	VCC-1.85 350	VCC-1.40			VCC-1.90 500	VCC-1.50	mV	IOL = -5 mA

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AC CHARACTERISTICS – PECL Input

 $\label{eq:VCC} Vsupply: \ VCC=VCC0=2.25\ to\ 3.80\ volts,\ VEE=0.0\ volts\ -OR-VCC=VCC0=0.0\ volts,\ VEE=-2.25\ to\ -3.80\ volts$ 

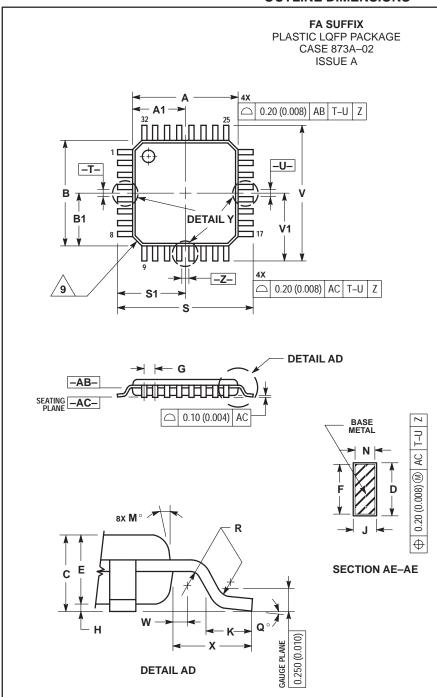
			-40°C			25°C			70°C			
Symbol	Characteristic	Min	typ	Max	Min	typ	Max	Min	typ	Max	Unit	Condition
Tpd	Differential propaga- tion delay											Nominal (single input condition VPP = 0.650V, VCMR = VCC-0.800V
	CLK0, CLK0 to all Q0, Q0 thru Q9, Q9	350		500	380		530	450		600	ps	Note 2
Tsk(part)	Part to part skew			150			150	İ		150	ps	Note 2
Tsk(out- put)	Output to output skew for given part		35	70		30	65		30	60	ps	Note 2
Tpd	Differential propagation delay  CLK0, CLK0 to all	280		600	300		620	370		700	ps	Note 2
	Q0,Q0 thru Q9,Q9											
Tsk(part)	Part to part skew			320			320			330	ps	Note 2
Tsk(out- put)	Output to output skew for given part		35	70		30	65		30	60	ps	Note 2
Fmax	Maximum frequency			1500			1500			1500	MHz	Functional to 1.5 GHz Timing specifications apply up to 1.0 GHz
Tr / Tf	Output rise and fall times (20%, 80%)	100		300	100		300	100		300	ps	All outputs terminated 500Ω to VCC–2.0V

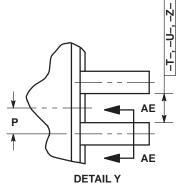
AC CHARACTERISTICS – HSTL Input

Vsupply: VCC=VCC0 = 2.25 to 3.8 volts, VEE = 0.0 volts

			–40°C			25°C			70°C			
Symbol	Characteristic	Min	typ	Max	Min	typ	Max	Min	typ	Max	Unit	Condition
Tpd	Differential propaga- tion delay											Nominal (single input condition Vdif = 1.000V, Vx = VEE+0.750V
	CLK1, CLK1 to all Q0, Q0 thru Q9, Q9	380		530	420		570	500		650	ps	Note 2
Tsk(part)	Part to part skew			150			150			150	ps	Note 2
Tsk(out- put)	Output to output skew for given part		35	70		30	65		30	60	ps	Note 2
Tpd	Differential propaga- tion delay CLK1,CLK1 to all	300		600	350		650	430		750	ps	All input conditions (full input range) Note 2
	Q0,Q0 thru Q9,Q9											
Tsk(part)	Part to part skew			300			300			320	ps	Note 2
Tsk(out- put)	Output to output skew for given part		35	70		30	65		30	60	ps	Note 2
Fmax	Maximum frequency			250			250			250	MHz	Functional to 250 MHz Timing specifications apply up to 250 MHz
Tr / Tf	Output rise and fall times (20%, 80%)	100		300	100		300	100		300	ps	All outputs terminated 500Ω to VCC–2.0V

#### **OUTLINE DIMENSIONS**





- NOTES:

  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

  CONTROLLING DIMENSION: MILLIMETER.

- 2. CONTROLLING DIMENSION: MILLIMETER.
  3. DATUM PLANE AB- IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.
  4. DATUMS –T., –U., AND –Z.—TO BE DETERMINED AT DATUM PLANE –AB-.
  5. DIMENSIONS S AND V TO BE DETERMINED AT SEATING PLANE –AC-.
  6. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.250 (0.010) PER SIDE. DIMENSIONS A AND B DO INCLUDE MOLD MINCLUDE MOLD MINCLUDE MOLD MINCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.250 (0.010) PER SIDE. DIMENSIONS A AND B DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE –AB-.
- DETERMINED AT DATUM PLANE AB-.

  7. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE D DIMENSION TO EXCEED 0.520 (0.020). 8. MINIMUM SOLDER PLATE THICKNESS SHALL BE
- 0.0076 (0.0003).

  9. EXACT SHAPE OF EACH CORNER MAY VARY
- FROM DEPICTION.

	MILLIN	IETERS	INC	HES			
DIM	MIN	MAX	MIN	MAX			
Α	7.000	BSC	0.276	BSC			
A1	3.500	BSC	0.138	BSC			
В	7.000	BSC	0.276	BSC			
B1	3.500	BSC	0.138	BSC			
С	1.400	1.600	0.055	0.063			
D	0.300	0.450	0.012	0.018			
Ε	1.350	1.450	0.053	0.057			
F	0.300	0.400	0.012	0.016			
G	0.800	BSC	0.031	BSC			
Н	0.050	0.150	0.002	0.006			
J	0.090	0.200	0.004	0.008			
K	0.500	0.700	0.020	0.028			
M	12°	REF	12° REF				
N	0.090	0.160	0.004	0.006			
Р	0.400	BSC	0.016 BSC				
Q	1°	5°	1°	5°			
R	0.150	0.250	0.006	0.010			
S	9.000	BSC	0.354 BSC				
S1	4.500	BSC	0.177 BSC				
V	9.000	BSC	0.354 BSC				
V1	4.500	BSC	0.177	BSC			
W	0.200	REF	0.008	REF			
Х	1.000	REF	0.039	REF			

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# **NOTES**

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