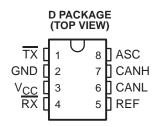
- SN75LBC031 Meets Standard ISO/DIS 11898 (up to 500 k Baud)
- Driver Output Capability at 50 mA
- Wide Positive and Negative Input/output Bus Voltage Range
- Bus Outputs Short-Circuit-Protected to Battery Voltage and Ground
- Thermal Shutdown

### description

The SN75LBC031 is a CAN transceiver used as an interface between a CAN controller and the physical bus for high speed applications of up to 500 kBaud. The device provides transmit capability to the differential bus and differential receive capability to the controller. The transmitter outputs (CANH and CANL), feature internal transition regulation to provide controlled symmetry resulting in low EMI emissions. Both transmitter outputs are fully protected against battery short circuits and electrical transients that can occur on the bus lines. In the event of excessive device power dissipation the output drivers are disabled by the thermal shutdown



#### **TERMINAL FUNCTIONS**

TERMINAL	DESCRIPTION
TX	Transmitter input
GND	Ground
VCC	Supply voltage
RX	Receiver output
REF	Reference output
CANL	Low side bus output driver
CANH	High side bus output driver
ASC	Adjustable slope control

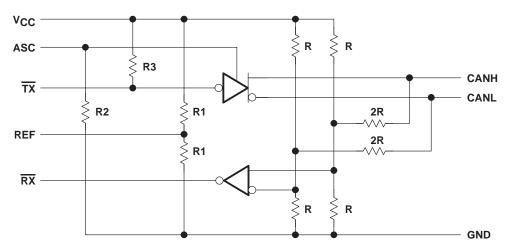
#### **FUNCTION TABLE**

TX	CANH	CANL	BUS STATE	RX
L	Н	L	Dominant	┙
High or floating	Floating	Floating	Recessive	Н

L = low, H = high

circuitry at a junction temperature of approximately  $160^{\circ}$ C. The inclusion of an internal pullup resistor on the transmitter input ensures a defined output during power up and protocol controller reset. For normal operation at 500 kBaud the ASC terminal is open or tied to GND. For slower speed operation at 125 kBaud the bus output transition times can be increased to reduce EMI by connecting the ASC terminal to  $V_{CC}$ . The receiver includes an integrated filter that suppresses the signal into pulses less than 30 ns wide.

### logic diagram





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## absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

Logic supply voltage, V <sub>CC</sub> (see Note 1)	7 V
Bus terminal voltage	
Input current at TX and ASC terminal, I <sub>1</sub>	
Input voltage at TX and ASC terminal, V <sub>I</sub>	
Operating free-air temperature range, T <sub>A</sub> : SN65LBC031	
SN75LBC031	-40°C to 85°C
Operating juncation range, T <sub>J</sub>	-40°C to 150°C
Continuous total power dissipation at (or below) 25°C free-air temperature See Dissipati	on Rating Table
Storage temperature range, T <sub>stq</sub>	-65°C to 150°C
Case temperature for 10 sec T <sub>C</sub> , D package	

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltage values, except differential bus voltage, are measured with respect to GND.

#### **DISSIPATION RATING TABLE**

PACKAGE	$T_{\mbox{\scriptsize A}} \le 25^{\circ}\mbox{\scriptsize C}$ POWER RATING	OPERATING FACTOR ABOVE T <sub>C</sub> = 25°C	T <sub>C</sub> = 125°C POWER RATING
D	725 mW	5.8 mW/°C	145 mW

### **DISSIPATION DERATING CURVE**

## FREE-AIR TEMPERATURE

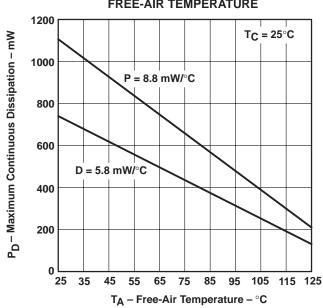


Figure 1

## SN65LBC031, SN75LBC031 HIGH-SPEED CONTROLLER AREA NETWORK (CAN) TRANSCEIVERS

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### recommended operating conditions

		MIN	NOM	MAX	UNIT
Logic supply voltage, V <sub>CC</sub>		4.5	5	5.5	V
Voltage at any bus terminal (separately or common mode), V <sub>I</sub> or V <sub>IC</sub> (see Note 3)				7	V
High-level input voltage, VIH	TX	2		Vcc	V
Low-level input voltage, V <sub>IL</sub>	TX	0		0.8	V
High level cutout current la	Transmitter			-50	mA
High-level output current, IOH	Receiver			-400	μΑ
Low lovel output output	Transmitter			50	A
Low-level output current, IOL	Receiver			1	mA
Operating free air temperature T.	SN75LBC031	-40		85	°C
Operating free-air temperature, T <sub>A</sub>	SN65LBC031	-40		125	C

NOTES: 2. All voltage values, except differential bus voltage, are measured with respect to the ground terminal.

3. For bus voltages from –5 V to –2 V and 7 V to 20 V the receiver output is stable.

### **SYMBOL DEFINITION**

DATA SHEET PARAMETER	DEFINITION
VO(CANHR)	CANH bus output voltage (recessive state)
VO(CANLR)	CANL bus output voltage (recessive state)
VO(CANHD)	CANH bus output voltage (dominant state)
VO(CANLD)	CANL bus output voltage (dominant state)
VO(DIFFR)	Bus differential output voltage (recessive state)
VO(DIFFD)	Bus differential output voltage (dominant state)
V <sub>I</sub> (ASC)	Adjustable slope control input voltage

# electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VO(REF)	Reference source output voltage	I <sub>REF</sub> = ±20 μA	0.45 V <sub>CC</sub>		0.55 V <sub>CC</sub>	V
RO(REF)	Reference source output resistance		5		10	kΩ
ICC(REC)	Logic supply current, recessive state	See Figure 2, S1 closed		12	20	mA
ICC(DOM)	Logic supply current, dominant state	See Figure 2, ST Closed		55	80	IIIA



# SN65LBC031, SN75LBC031 HIGH-SPEED CONTROLLER AREA NETWORK (CAN) TRANSCEIVERS

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# transmitter electrical characteristics over recommended ranges of supply and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VO(CANHR) VO(CANLR)	Output voltage (recessive state)	See Figure 2, S1 open	2	0.5 V <sub>CC</sub>	3	V
VO(DIFFR)	Differential output voltage (recessive state)		-500	0	50	mV
VO(CANHD)	Output voltage (dominant state)		2.75	3.5	4.5	
VO(CANLD)	Output voltage (dominant state)	See Figure 2, S1 closed	0.5	1.5	2.25	V
VO(DIFFD)	Differential output voltage (dominant state)		1.5	2	3	
	High-level input current (TX)	V <sub>IH</sub> = 2.4 V		-100	-185	μΑ
IH(TX)	riigii-ievei iriput current (177)	V <sub>IH</sub> = V <sub>CC</sub>			±2	μΑ
lu va oo	High level is not suggest (ACC)	V <sub>IH</sub> = 2.4 V		100	165	
IH(ASC)	High-level input current (ASC)	VIH = VCC		200	340	μΑ
I <sub>IL(TX)</sub>	Low-level input current (TX)	V <sub>IL</sub> = 0.4 V		-180	-400	μΑ
I <sub>IL</sub> (ASC)	Low-level input current (ASC)	V <sub>IL</sub> = 0.4 V		15	25	μΑ
C <sub>I(TX)</sub>	TX input capacitance			8		pF
I <sub>O(ssH)</sub>	CANH short circuit output current	$V_{O(CANH)} = -2 V \text{ to } 20 V$		-95	-200	mA
I <sub>O(ssL)</sub>	CANL short circuit output current	V <sub>O(CANL)</sub> = 20 V to −2 V		140	250	mA

NOTE 2: All voltage values, except differential bus voltage, are measured with respect to the ground terminal.

# transceiver dynamic characteristics over recommended operating free-air temperature range and $V_{\text{CC}}$ = 5 V

	PARAMETER	TEST	CONDITIONS	MIN	TYP	MAX	UNIT
	Laur Care	See Figures 2 and 3, S1 closed,	V <sub>I</sub> (ASC) = 0 V or open circuit, S2 open			280	ns
<sup>t</sup> (loop)	Loop time	See Figures 2 and 3, S1 closed,	V <sub>I</sub> (ASC) = V <sub>CC</sub> , S2 closed			400	ns
SD (==)	Differential-output slew rate (recessive to dominant)	See Figures 2 and 4, S1 closed,	V <sub>I(ASC)</sub> = 0 or open circuit, S2 open		35		V/μs
SR <sub>(RD)</sub>		See Figures 2 and 4, S1 closed,	VI(ASC) = VCC, S2 closed		10		V/μs
CD	Differential-output slew rate (dominant to recessive)	See Figures 2 and 4, S1 closed,	V <sub>I(ASC)</sub> = 0 or open circuit, S2 open		10		V/μs
SR <sub>(DR)</sub>		See Figures 2 and 4, S1 closed,	VI(ASC) = VCC, S2 closed		10		V/μs
t <sub>d</sub> (RD)	Differential-output delay time	See Figure 2,	S1 closed		55		ns
t <sub>d(DR)</sub>	Differential-output delay time	Gee Figure 2,	31 Cl0560		160		ns
tpd(RECRD)	Receiver propagation delay	See Figures 2 and 5			90		ns
tpd(RECDR)	time	oee rigules 2 and 5			55		ns

NOTE 4: Receiver input pulse width should be >50 ns. Input pulses of <30 ns are suppressed.



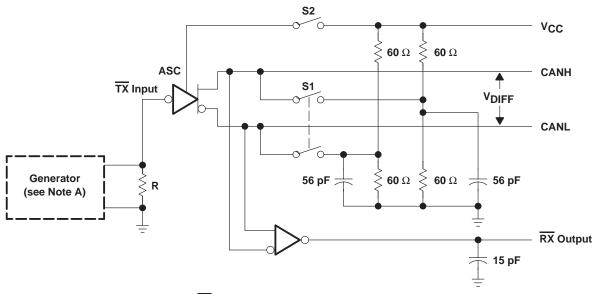
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# receiver electrical characteristics over recommended ranges of common-mode input voltage, supply voltage, and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VIT(REC)	Differential input threshold voltage for recessive state	V <sub>IC</sub> = -2 V to 7 V			500	mV
VIT(DOM)	Differential input threshold voltage for dominant state	\( \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \(	900			IIIV
V <sub>hys</sub>	Recessive-dominant input hysteresis		100	180		mV
VOH(RX)	High-level output voltage	$V_{O(DIFF)} = 500 \text{ mV},$ $I_{OH} = -400 \mu\text{A}$	V <sub>CC</sub> -0.5 V		VCC	V
V <sub>OL(RX)</sub>	Low-level output voltage	$V_{O(DIFF)} = 900 \text{ mV},$ $I_{OL} = 1 \text{ mA}$	0		0.5	V
rI(REC)	CANH and CANL input resistance in recessive state	dc, no load	5		50	kΩ
rl(DIFF)	Differential CANH and CANL input resistance in recessive state	dc, no load	10		100	kΩ
Ci	CANH and CANL input capacitance			20		pF
C <sub>i(DHL)</sub>	Differential CANH and CANL input capacitance			10		pF

NOTE 2: All voltage values, except differential bus voltage, are measured with respect to the ground terminal.

### PARAMETER MEASUREMENT INFORMATION

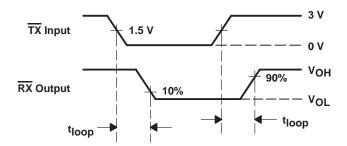


NOTE A: The input pulse is supplied to  $\overline{TX}$  by a generator having a  $t_f$  and  $t_f = 5$  ns.

Figure 2. Test Circuit

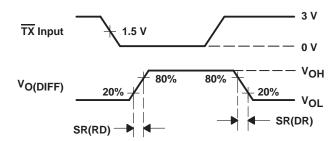


### PARAMETER MEASUREMENT INFORMATION



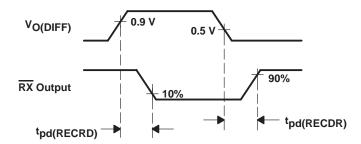
NOTE A: The input pulse is supplied to  $\overline{TX}$  by a generator having a  $t_\Gamma$  and  $t_f=5$  ns.

Figure 3. Loop Time



NOTE A: The input pulse is supplied to  $\overline{TX}$  by a generator having a  $t_f$  and  $t_f=5$  ns.

Figure 4. Slew Rate



NOTE A: The input pulse is supplied as  $V_{DIFF}$  using CANH and CANL respectively by a generator having a  $t_r$  and  $t_f = 5$  ns.

Figure 5. Receiver Delay Times



### PARAMETER MEASUREMENT INFORMATION

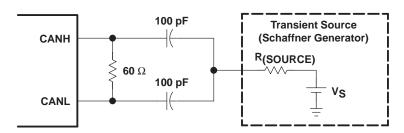


Figure 6. Transient Stress Capability Test Circuit

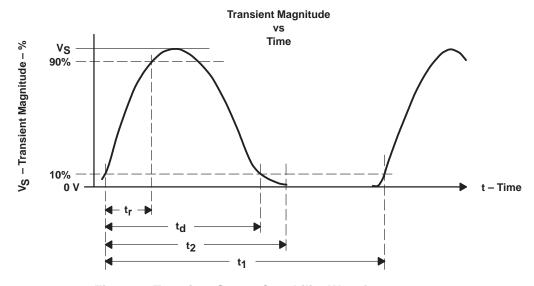


Figure 7. Transient Stress Capability Waveform

Table 1. Test Circuit Results According to DIN 40839

TEST PULSE	TRANSIENT MAGNITUDE V <sub>S</sub>	SOURCE IMPEDANCE RSOURCE	PULSE WIDTH t <sub>d</sub> (see Note 5)	PULSE RISE TIME, t <sub>r</sub> (see Note 6)	PULSE TIME, t <sub>2</sub> (see Figure 7)	REPETITION PERIOD, t <sub>1</sub> (see Figure 7)	NUMBER OF PULSES
1	–100 V	10 Ω	2 ms	1 μs	200 ms	5 s	5000
2	100 V	10 Ω	50 μs	1 μs	200 ms	5 s	5000
3a	–150 V	50 Ω	0.1 μs	5 ns	100 μs	100 μs	See Note 7
3b	100 V	50 Ω	0.1 μs	5 ns	100 μs	100 μs	See Note 7
5	60 V	1 Ω	400 ms	5 ms	_	_	1

NOTES: 5. Measured from 10% on rising edge to 10% on falling edge

6. Measured from 10% to 90% of pulse

7. Pulse package for a period of 3600 s, 10 ms pulse time, 90 ms stop time

### **APPLICATION INFORMATION** < 100 nF 3 120 $\Omega$ 10 $\mathbf{k}\Omega$ 8 10 kΩ ≤ VCC **VCC** ASC 8 TL7705B **CANH** 7 SENSE SN75LBC031 2 RESIN RESET GND CANL **REF GND** Cin REF TX RX $\mathbf{120}\;\Omega$ $0.1 \mu F$ **CAN Microcontroller**

Figure 8. Typical SN75LBC031 Application



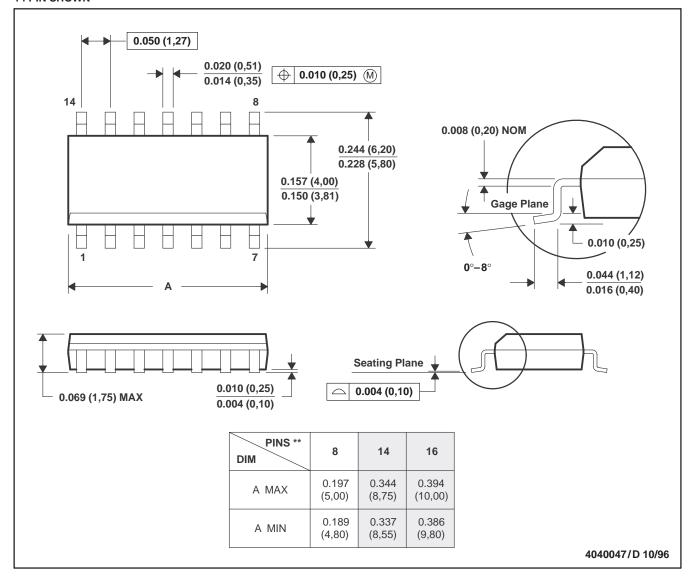
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### **MECHANICAL DATA**

### D (R-PDSO-G\*\*)

### 14 PIN SHOWN

### PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-012

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