

Generating a Custom-Ready Signal Using the NS32GX32 Evaluation Board

AN-633

Two other jumpers are shown in *Figure 1*. Jumper W2.1 removes all wait states for high speed static RAM accesses. Jumper W2.2 selects between normal (real-time) or single-step operation.

3.0 USING USER0

Figure 2 shows the worst-case timing at 30 MHz with USER0 selected. The CONF signal is used to clear the J-K flip-flop in state T1 of the bus cycle and to initialize the RDY input signal to the ready state. The J input is high for I/O accesses and the K input is valid at least 6.8 ns before the falling edge of $\overline{\text{CLK1}}$. Therefore, the Q output will toggle with both J and K at logic state 1 and RDY will switch to the not ready state. A single wait state will be inserted into the cycle since $\overline{\text{RDY}}$ will be set up for at least 19 ns before the rising edge of state T2W.

The $\overline{\text{RDY}}$ signal will then become active or back to the ready state after the next falling edge of CLK1 since the J-K flip-flop will toggle again. The bus cycle will then be completed, since $\overline{\text{RDY}}$ will be sampled active on the rising edge of state T1.

4.0 USING CUSTOM-READY ($\overline{\text{CRDY}}$)

If custom-ready ($\overline{\text{CRDY}}$) is selected to control the micro-processor's $\overline{\text{RDY}}$ signal, then the user can generate the number of wait states required for a particular application. An example of a custom-ready circuit is shown in *Figure 3*.



FIGURE 1. NS32GX32 Evaluation Board Ready Circuit

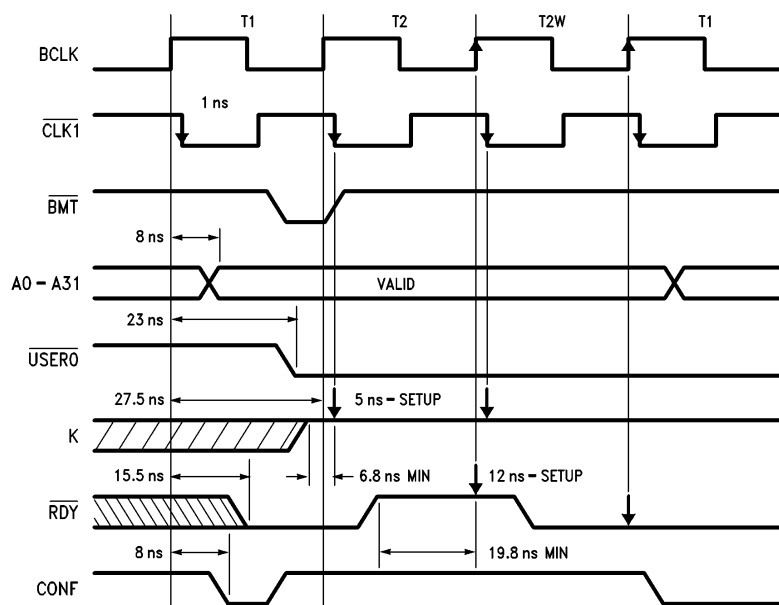


FIGURE 2. Worst-Case Timing at 30 MHz with $\overline{\text{USER0}}$

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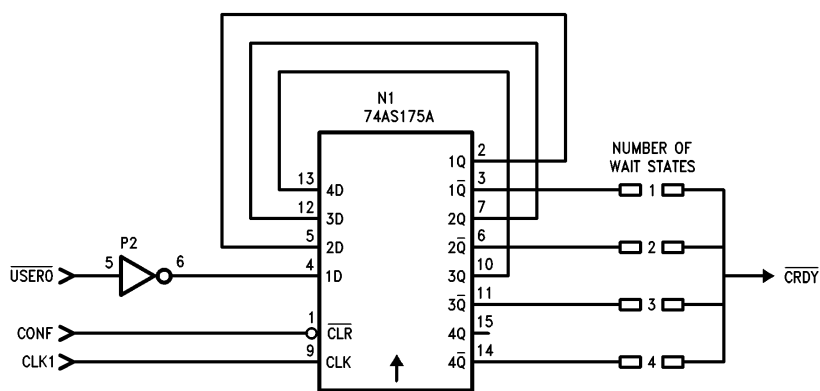


FIGURE 3. A Custom-Ready Circuit

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In this example, a single 74AS175A quad D flip-flop package and an inverter for the designer kit's $\overline{\text{USER0}}$ signal provides four wait state options. One to four wait states can be inserted into each I/O bus cycle for the $\overline{\text{USER0}}$ address space by installing the appropriate jumper for the $\overline{\text{CRDY}}$ signal. Figure 4 shows the worst-case timing at 30 MHz with $\overline{\text{CRDY}}$ selected.

The timing diagrams show maximum propagation delays and minimum setup time requirements. At the beginning of a new bus cycle (state T1), the confirm bus cycle signal ($\overline{\text{CONF}}$) initializes the custom ready to the "not ready" state ($\overline{\text{CRDY}} = 1$), and the microprocessor's ready signal to the ready state ($\text{RDY} = 0$).

In state T2, since the setup requirement of at least 5 ns is satisfied by the K input, the microprocessor's ready signal will switch to the "not ready" state ($\text{RDY} = 1$).

A T2 wait state (T2W state) will be inserted into the bus cycle since the setup requirement of at least 12 ns will be satisfied by the RDY input. Depending on which jumper is installed, either another T2W state will be inserted, or the cycle will end since the K input will switch to the high state, forcing the Q output of the J-K flip-flop to toggle the ready input back to the ready state ($\text{RDY} = 0$).

CLK1 is a delayed bus clock signal (BCLK), used to trigger each stage of the 74AS175A quad D flip-flop package on its rising edge. $\overline{\text{USER0}}$ is a chip select and is used as the source for the custom-ready logic. The $\overline{\text{CONF}}$ signal is extended along with the bus cycle and clears all flip-flops simultaneously at the end of the complete cycle.

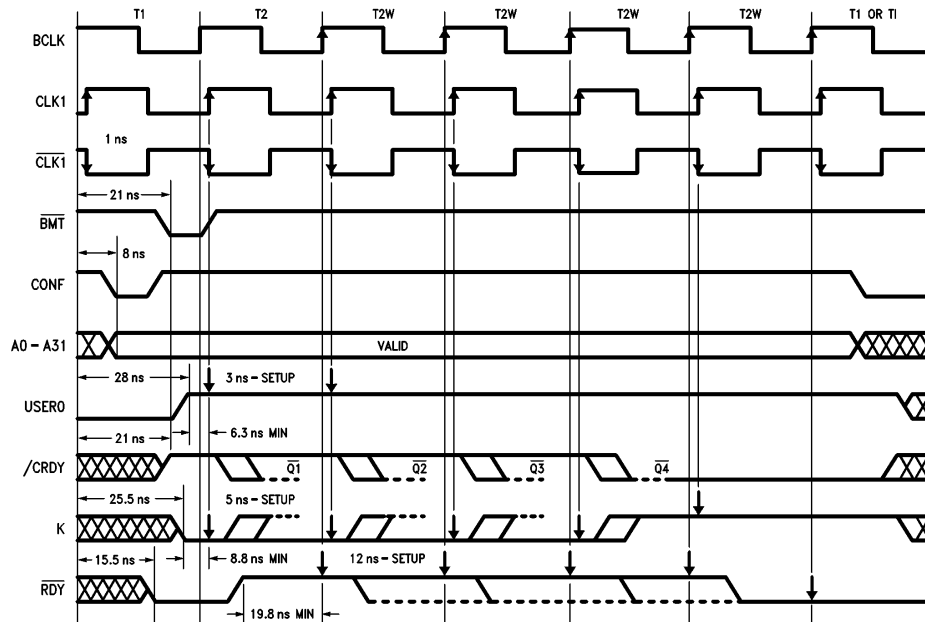


FIGURE 4. Worst-Case Timing at 30 MHz with $\overline{\text{CRDY}}$

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